

## Technical Data Sheet Prosthetics Hand Release Version 1.1 October 2024

#### **Product Name:**

The Genesis Hand

## **Key Features:**

- ✓ Visual Feedback Indicator
- 1.2s closing speed
- 6 Powered DOFs
- Fully Modular Fingers
- Multifunction Push Button
- 15lbs Lifting Capacity
- Single or Dual Site EMG Control
- < 1mm Finger Position Repeatability</p>

# **Product Summary:**

The Genesis Hand is a 6 degree-of-freedom myoelectric / powered upper limb device developed for prosthetic applications. The Genesis Hand is equipped with a variety of advanced features that were inspired by feedback from the upper limb loss community, prosthetists, and upper limb specialists. The hand was designed to provide an affordable alternative to current powered hands while also maintaining advanced functionalities, reducing learning curves, and most importantly, helping amputees live a more independent lifestyle.









| Mechanical Specifications   |   |
|-----------------------------|---|
| Specification               | Value   |
| Dimensions (Medium)         | 7.7" H x 4.3" W x 2.2"  |
| Weight                      | 1.0 lb.   |
|                             |   |
| Max Grip Force (Power Grip) | 13N   |
| Max Grip Speed (Power Grip) | 1.2 seconds   |
| Maximum Carrying Capability | 15lbs (Power Grip + Hand Lock)  |
|                             |   |
| Thumb Type                  | Powered (2 Degrees of Freedom)  |
| Thumb Rotation Speed        | 1.2 seconds to full stroke rotation   |
| Thumb Flexion Speed         | 1.2 seconds to full stroke flexion  |
| Finger Flexion Speed        | 1.0 seconds to full stroke flexion  |
|                             |   |
| Water Resistance            | Unofficial IP54 - Resistant to limited dust and splashes.<br>Best for indoor areas, avoid rain. |
|                             | Best for filedor areas, avoid fam.  |
| Electrode Configuration     | Single or Dual Site   |
| Grip Patterns               | 4 Core  |
| Custom Grip Patterns        | Infinite  |
| Connection Type             | 6-Pin EQD (Compatible with 4-Pin Coax)  |
|                             |   |
| Feedback Mechanisms         | Visual Only   |



| General Specifications     |   |
|----------------------------|---|
| Grip Patterns              | 4 Core  |
| Custom Grip Patterns       | Infinite  |
|                            |   |
| Single-Site Control Method | <b>Double Button Press = Change Grip</b>  |
|                            | Polmor Floy - Close Crip  |
|                            | Palmar Flex = Close Grip Wait 1.5s  |
|                            | Palmar Flex = Open Grip   |
|                            | 1 1   |
|                            | Grip can also be changed via app  |
|                            |   |
| Dual-Site Control Method   | When No Grip Is Activated   |
|                            | -   |
|                            | Single Palmar Flex = Core Grip 1  |
|                            |   |
|                            | Single Palmar Flex = Core Grip 1  |
|                            | Single Palmar Flex = Core Grip 1  Double Palmar Flex = Core Grip 2  |
|                            | Single Palmar Flex = Core Grip 1  Double Palmar Flex = Core Grip 2  Single Dorsal Flex = Core Grip 3  |
|                            | Single Palmar Flex = Core Grip 1  Double Palmar Flex = Core Grip 2  Single Dorsal Flex = Core Grip 3  Double Dorsal Flex = Core Grip 4  |
|                            | Single Palmar Flex = Core Grip 1  Double Palmar Flex = Core Grip 2  Single Dorsal Flex = Core Grip 3  Double Dorsal Flex = Core Grip 4  When Core Grip Activated  |
|                            | Single Palmar Flex = Core Grip 1  Double Palmar Flex = Core Grip 2  Single Dorsal Flex = Core Grip 3  Double Dorsal Flex = Core Grip 4  When Core Grip Activated  Palmar Flex = Close Grip  Dorsal Flex = Open Grip                         |
|                            | Single Palmar Flex = Core Grip 1  Double Palmar Flex = Core Grip 2  Single Dorsal Flex = Core Grip 3  Double Dorsal Flex = Core Grip 4  When Core Grip Activated  Palmar Flex = Close Grip  |
|                            | Single Palmar Flex = Core Grip 1  Double Palmar Flex = Core Grip 2  Single Dorsal Flex = Core Grip 3  Double Dorsal Flex = Core Grip 4  When Core Grip Activated  Palmar Flex = Close Grip  Dorsal Flex = Open Grip  When Core Grip Is Open |



### **General Specifications (Continued)**

Warranty 1-Year Limited

**Operational Lifetime:** The lifetime of a finger (or thumb) depends mainly on the conditions during operation. The total hours of operation can therefore vary greatly from some hundreds of hours under extreme conditions to over 10,000 hours under optimal conditions. Under typical load conditions a finger will have an operational lifetime anywhere between 1,000 to 5,000 running hours.

**PDAC**: Pending PDAC Approval – L6880

#### Who Should Use The Genesis Hand?

The Genesis Hand is specifically designed for adult transradial amputees (aged 18 and above) seeking a reliable and functional prosthetic solution for everyday tasks. While adaptable for use by bilateral amputees, the Genesis Hand excels when used by individuals with unilateral transradial amputations or congenital differences.

It is important to note that the device is not intended for people who regularly engage in high-impact activities such as frequently lifting weights exceeding 15 lbs, mountain biking, or other extreme sports. This focus ensures that the hand maintains its longevity and performance, offering a balance of functionality and ease of maintenance for everyday tasks and moderate physical activities.

This information is provided to help both clinicians and amputees understand the optimal use conditions for The Genesis Hand, ensuring it delivers the highest levels of comfort, utility, and satisfaction for the intended patient population.